System description — Dimensioning

SINAMICS S120 Control Units

Configuration

Typical slip values for standard asynchronous motors (induction motors)

(madelion motors)				
Motor output	Slip values	Notes		
< 1 kW (1.34 HP)	6 % of <i>n</i> _{rated} e.g. motor with 1500 rpm: 90 rpm	The slip values of 1PH asynchronous motors are very similar to those		
< 10 kW (13.4 HP)	3 % of <i>n</i> _{rated} e.g. motor with 1500 rpm: 45 rpm	of standard motors		
< 30 kW (40.2 HP)	2 % of n _{rated} e.g. motor with 1500 rpm: 30 rpm			
< 100 kW (134 HP)	1 % of n _{rated} e.g. motor with 1500 rpm: 15 rpm			
> 500 kW (671 HP)	0.5 % of n _{rated} e.g. motor with 1500 rpm: 7.5 rpm			

Performance of integrated closed-loop drive control with SIMOTION D4x5/CX32 (closed-loop drive control based on firmware version 2.x)

The degree to which the capacity of the closed-loop drive control with SIMOTION D4x5/CX32 is utilized depends on requirements in terms of number of axes, functional scope and control dynamic response.

When additional software functions (DCC, Safety, etc.) are activated and other components (Terminal Modules, CX32, ...) are employed, fewer axes can be computed by the integrated closed-loop drive control. With the SIZER configuration tool, it is

easy to configure the SINAMICS S120 drive family including SIMOTION D. It can also be used to determine the possible number of axes and the resulting load according to performance requirements.

The following table provides a rough overview of computing performance as a function of current controller clock cycle (dynamic response) and number of axes with basic scope of functions (factory setting).

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	Dynamic response (current controller clock cycle)	Number of axes	Note	
Servo Control	125 µs	6	Including one infeed (Basic Line Module, Smart Line Module,—Active Line Module). Number of axes applies only to basic functionality. Without expanded setpoint channel. Note power unit derating where applicable.	
	250 μs	6		
Vector Control	250 μs	2	Including one infeed (Basic Line Module, Smart Line Module, Active Line Module).	
	500 μs	4	Number of axes applies only to basic functionality. Expanded setpoint channel included as standard. Note power unit derating where applicable.	
V/f Control	250 μs	4	Including one infeed (Basic Line Module, Smart Line Module,	
	400 μs	6	—Active Line Module). —Number of axes applies only to basic functionality.	
	500 μs	8	Expanded setpoint channel included as standard.	
Mixed operation				
Servo Control plus V/f Control	125 μs + 250 μs/500 μs	5	Including one infeed (Basic Line Module, Smart Line Module, Active Line Module).	
			Maximum 2 $V\!f$ axes with 250 μ s current controller clock cycle, otherwise divide as required.	
Vector Control plus V/f Control	250 μs/500 μs	2/4	Including one infeed (Basic Line Module, Smart Line Module, Active Line Module). In mixed operation Vector with V/f no difference to pure Vector operation.	