# **SIEMENS**

# **Quick Installation Guide**

# SINAMICS S210 1 AC 230 V

# **Edition 12/17**

# WARNING

Danger to life if the safety instructions and installation instructions are not observed The Quick Installation Guide only contains the most important information for the installation of the converter. If the safety instructions and installation instructions in the associated documentation are not observed, accidents involving severe injuries or death can occur.

Observe the safety instructions and installation instructions given in the associated operating instructions: <u>www.siemens.com/sinamics-s210</u>

Also observe the safety instructions for the integrated functional Safety functions. Make sure that these functions are fully operational again after replacing a converter.

## A DANGER

Danger to life through electric shock due to residual charge in the dc link capacitors Because the DC link capacitors, a hazardous voltage is present for up to 5 minutes after the power to the converter has been removed.

- Ontact with live parts of the converter can result in death or serious injury.
   On ot open the protective covers or the terminal covers until 5 minutes after the power has been removed
- Before starting any work, check that the system is in a voltage-free state by measuring all terminals,
- including to ground.
  Ensure that the associated warning labels, in the approropriate languages, are attached.

## **Technical data**

Order number:		6SL3210- 5HB10-1UF0	6SL3210- 5HB10-2UF0	6SL3210- 5HB10-4UF0	6SL3210- 5HB10-8UF0					
Line supply										
Line voltage		1 AC 200 240 V ±10 %								
<ul> <li>Input frequency</li> </ul>	Hz	50/60								
Rated input current	Α	1,4	2,7	5	9,3					
Inrush current	Α	8.0	8.0	8.0	8.0					
Power dissipation	W	7	14	28	52,5					
Electronic supply										
<ul> <li>Ext. supply voltage</li> </ul>		24 V -15 % +2	0 %							
<ul> <li>Current, max.</li> </ul>	А	1,6								
Output for motor										
Rated power	kW	0,1	0,2	0,4	0,75					
<ul> <li>Rated output current</li> </ul>	Α	0,8	1,36	2,4	4,4					
Output current, max.	А	3,1	4,8	8,7	16					
Pulse frequency	kHz	8								
Output frequency	Hz	0 550								
EMC filter (integrated)		Category C2 (≤	10 m) / Category (	C3 (≤ 25 m)						
Brake resistor		None 1)	None 1) Integrated Integrated Integrated							
Digital inputs		2 Measuring probes or Reference marks     1 Failsafe input (F-DI)     1 Temperature monitor for ext. brake resistor								
Cooling		Convection (with								
Frame Size		FSA	FSA	FSB	FSC					
Dimensions										
• Width	mm	45	45	55	70					
• Hight	mm	170	170	170	170					
• Depth	mm	170	170	170	195					
Weight, approx.	kg	1,1	1,1	1,2	1,9					
Climatic conditions for operation		0 50 °C, Relat and ice formatio Up to max, 4000	n not permitted	95 % condensation	on, spraying water					
Installation altitude		Up to 1000 m a     Above 1000 m     Above 2000 m	bove sea level w/ Derating 10 % cu Isolation-transfor	rrent or 5 K per 10	100 m					
Pollution degree		2 (according to E	N 6180051)							
Protection acc. EN60529		IP20, Must be in	stalled in a contro	l cabinet						
Short-circuit current (SCCR)		≤ 65 kA rms								
Fuse according to IEC		3NA3 801 (6 A)	3NA3 801 (6 A)	3NA3 803 (10 A)	3NA3 805 (16 A)					
Fuse according to UL, classes	2	6 A	6 A	10A	20A					
Directives and Standards		CE, cULus, RCM								
1) Due to the available DC-Link cap										

2)Any class from class J, T, CC, G, etc., which are equal or better than Class RK5 fuses

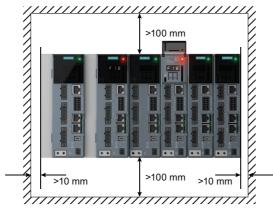
### Mounting the converter

The converter may be operated only in closed housings or in higher-level control cabinets with protective covers that are closed, and when all of the protective devices are used. The installation of the converter in a metal control cabinet or the protection with another equivalent measure must prevent the spread of fire and emissions outside the control cabinet.

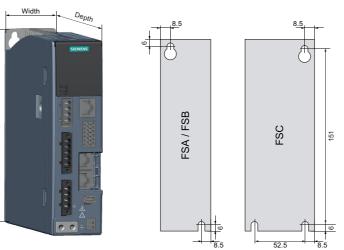
Protect the converter, e.g. by installing it in a control cabinet with degree of protection IP54 according to IEC 60529 or NEMA 12. Further measures may be necessary for particularly critical operating conditions. If condensation or conductive pollution can be excluded at the installation site, a lower degree of control cabinet protection may be permitted.

Leave a minimum 100 mm clearance to other devices at the top and bottom. A lateral clearance between multiple SINAMICS S210 converters is not mandatory. Observe a lateral clearance of at least 10 mm to other devices.

## **Clearance distances**



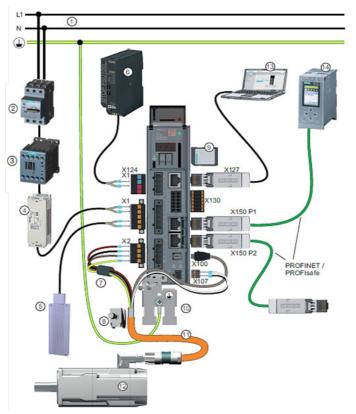
### Dimensional drawings and drill dimensions



# Dimensions

Frame size	Width (mm)	Height (mm)	Depth (mm)	Weight (kg)
FSA	45	170	170	1.1
FSB	55	170	170	1.2
FSC	70	170	195	1.9

# System overview



# System overview (cont'd)

1	Line supply 230 V	8	Shield clamps
2	Fuse and circuit breaker	9	SD-memory card (optional)
3	Line contactor (optional)	10	Shielding plate
4	Line filter (optional)	1	OCC - connecting cable for Motor Holding Brake and encoder
5	External braking resistor (optional)	12	Servomotor 1FK2
6	Power supply 24 V	13	Commissioning using PC
0	Ferrite core	14	Control example; SIMATIC S7-1500 PLC

### Connection the converter

Install the converter so that you comply with local regulations for erecting and installing low voltage systems.

# Notes

Operating displays for converter operation If, when switching over a function from ON to OFF, an LED or other similar display is not lit or not active; this does not indicate that the device is switched-off or in a no-current condition.

Converter is grounded (earthed) correctly Make sure that the shield of the motor cable is properly grounded (earth). Use the shielding clamp which comes with the cable to mount the cable to the converter's shielding plate

#### Safety devices

Install suitable protective equipment between the line supply and converter.

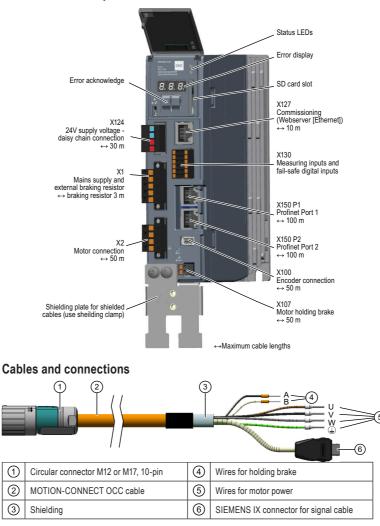
Protection and monitoring equipment To provide protection against short-circuit, use the overcurrent devices listed in the Technical data (fuses, circuit breakers etc.).

If the apparent impedance of the line supply at the infeed point is not suitable, so that fuses do not rupture in the specified time in the case of insulation failure (ground fault, fault to frame), then you must use additional residual current protective devices RCD (RCCB or MRCD), type B.

To prevent an RCD from unnecessarily tripping as a result of operational leakage currents, the following preconditions must be fulfilled: · The neutral point of the line supply is grounded.

- · Use an RCCB type B with a response limit current of 300 mA. Connect the RCCB in series with the
- overcurrent protective devices.
- Use a separate RCD for each converter
- The motor cables are shorter than 50 m (164 ft) shielded.

### Connections and operator controls on the converter



# **SINAMICS S210 FSA - FSC Edition 12/17**

#### X1: Line connection and connection for external braking resistor

			•
	Pin	Connection for	Explanation
		Phase L1 line system	
0		Neutral conductor	
3	DCP		If you are using the internal braking resistor, DCP and R2 must be jumpered.
3	R2	Internal braking resistor	If you are using the external braking resistor, remove the jumper between DCP and R2.
	R1		Connect the external braking resistor by means of terminals DCP and R1
Veidmuller: B	LF 5.08	HC/05/180F SN BK BX. article	e number 1012670000

As daisy chain: BLDF 5.08/05/180F SN BK BX, article number 1000970000

The terminals are spring-type terminals

Permissible conductor cross-sections for single-core connection or for the connection of flexible cables with end sleeves:
0.2 mm<sup>2</sup> ... 2.5 mm<sup>2</sup>

• AWG: 26 ... 12

#### X2: Power connections for the motor

Pin	Pin assignment	Colour coding for Siemens OCC cables
U	Motor phase U	Brown
V	Motor phase V	Black
W	Motor phase W	Gray
PE	Protective ground	Green-yellow
	U V W	U         Motor phase U           V         Motor phase V           W         Motor phase W

Weidmuller: BLF 5.08HC/05/180F SN BK BX, article number 1012660000

The terminals are spring-type terminals

Permissible conductor cross-sections for single-core connection or for the connection of flexible cables with end sleeves: 0.2 mm<sup>2</sup>
 2.5 mm<sup>2</sup>

• AWG: 26 ... 12

### X100: Siemens IX connector: Encoder connection

	Pin	Pin assignment	Explanation
	1	TXP	Sending data + / encoder power supply M
	2	TXN	Sending data - / encoder power supply M
	3	Reserved	
	4	Reserved	
	5	Reserved	
	6	RXP	Receiving data + / encoder power supply P24+
	7	RXN	Receiving data + / encoder power supply P24+
	8	Reserved	
	9	Reserved	
	10	Reserved	
Siemens IX, a	rticle nu	mber 6FX2003-0DE01	

#### X107: Motor holding brake

		•							
	Pin	Pin assignment	Explanation						
	BR-	В-	Voltage for motor holding brake, 0 V (white)						
	BR+	B+	Voltage for motor holding brake, 24 V (black)						
Phoenix 17/15	Phoenix 17/580/ EMC 1.5 / 2-ST-3.81 article number 17/580/								

enix 1/45894 FMC 1.5 / 2-S1-3.81, article number 1/45894

The terminals are spring-type terminals. Permissible conductor cross-sections: for single-core connection or for flexible cables with end sleeves without plastic protection: • 0.25 mm<sup>2</sup> ... 1.5 mm<sup>2</sup>, AWG: 24 ... 16

for flexible cables with end sleeves with plastic protection: • 0.25 mm<sup>2</sup> ... 0.75 mm<sup>2</sup>, AWG: 24 ... 19

Connect the wires for the holding brake to the connector X107 also if you are using a motor without holding brake

#### X124: 24 VDC control voltage

	Pin		Explanation
	М	0 V	Power supply for the converter electronics
13-1	М	0 V	
B	L+	24 V	
	L+	24 V	
Dinkle: article	numbe	r A000101686	

The terminals are spring-type terminals. Permissible conductor cross-sections for single-core connection or for the connection of flexible cables with end sleeves: • 0.2 mm<sup>2</sup> ... 2.5 mm<sup>2</sup>

AWG: 26 ... 12

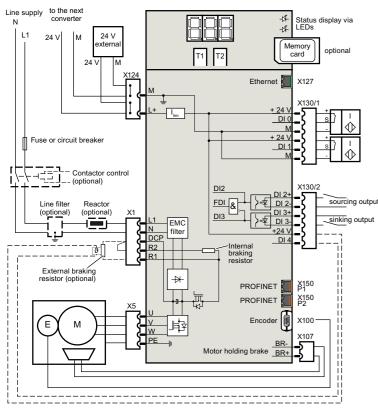
## X130: Connector for digital inputs

	Pin	Pin assignment	Pin assignment	Pin
	L+	24 V supply		D1 2+
	DI 0 High-speed DI, measuring input		Fail aafa diaital innuta	D1 2-
	М	Ground	Fail-safe digital inputs	DI 3+
1331	L+	24 V supply		DI 3-
TCCI	DI 1	High-speed DI, measuring input	24 V supply	L+
	М	Ground	Digital input	DI 4
Dinkle: article	numh	ar A000101686	· ·	

The terminals are spring-type terminals.

- Permissible conductor cross-sections:
   for single-wire connection: 0.2 mm<sup>2</sup> ... 1.5 mm<sup>2</sup>, AWG: 24 ... 16
   for flexible cables with end sleeves: 0.25 mm<sup>2</sup> ... 1.5 mm<sup>2</sup>, AWG: 24 ... 16
- for flexible cables with end sleeves with plastic protection: 0.25 mm<sup>2</sup>... 0.75 mm<sup>2</sup>, AWG: 24 ... 19

## Block diagram



### Commissioning

Commissioning with web server Use the web server integrated in the converter for the commissioning. The Web server integrated in the converter supports the following browsers:

- Microsoft Internet Explorer 11
- Microsoft Edge ≥ V14
- Mozilla Firefox ≥ 48
- Google Chrome ≥ V52

- Preparation for commissioning

  Mount the motor on the mechanical system. Connect the motor to the converter. · Connect the converter to your Commissioning-PC via the Ethernet interface (X127).
- Switch the converter on.
- The converter powers up and reads the motor data.
- Start the Internet-Browser for commissioning
- · Enter the IP address of the converter in the input line of your browser. Default-IP-Address: 169.254.11.22 (Subnet-Mask: 255.255.0.0).

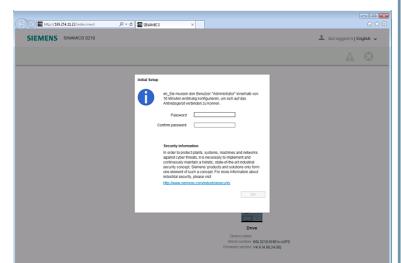
#### Note

If the RDY LED is blinking fast in yellow after the first power up of the converter, then a power cycle is required after an update of a motor component. Turn the 24V supply of the converter off and back on again.

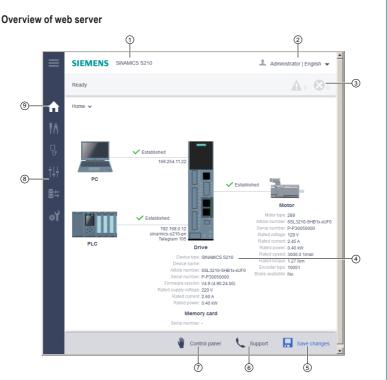
#### Assigning an Administrator password

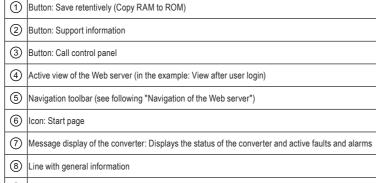
In order to get full access to the converter you have to log-in as Administrator. For the access as Administrator a password is required. After powering up the converter a dialog to enter the Administrator password appears for 10 min. The following mask appears only if the Administrator password has not been assigned and only for the duration of 10 minutes after powering up the converter. Assign an Administrator password.

Note Note down the password and store it carefully in a secure place!



After assigning the Administrator password the Log-in page is displayed. Enter the login "Administrator" and the password which you have assigned in the step before. After a successful log-in the Overview page appears.





Drop-down list for the language selection and to log out from the Web server.

For more detailed information, please refer to the S210 Operating Instructions

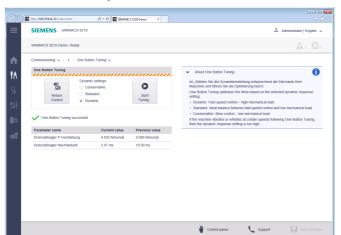
# WARNING

Danger due to moving parts of the machine During the following steps the motor will rotate. Please make sure that the motor is mounted and connected correctly and that the connected mechanics may be moved without causing a damage or injury.

### Perform a One-Button-Tuning

For the optimization of the control parameters, perform the following procedure 1. Select 'Commissioning'

- Select 'Tuning'
- Click on "Take Control" and confirm the confirmation prompt (Orange/white bar appears).
- Choose a Dynamic setting according to the mechanical capabilities of your machine. Click on "Start tuning".
- Enter the permissible angle of rotation for the required measurement about which the motor and the connected machine are permitted to turn without causing a damage to the mechanics (the angle 6. should at least be 60°, a greater angle leads to better results). Confirm with OK and the tuning will start.



### Control panel

If it is required to move the axis this can be done using the control panel. Click on the button 'Control panel' in the footer, take over the control and enter the desired speed. Now the axis can be moved by holding the 'Rotate Left/Right' buttons.

### Additional functions

Further adjustments can be made by selecting the menu item 'Parameters'.

You can also save the parameter settings and restore them later if required or you can reset the converter to the factory defaults.

In the 'System' menu you can change passwords and enable the access to the web server via the

Saving changes In order to save the changes permanently click on the floppy disk symbol in the footer.

Messages In the menu choose 'Diagnostics' and 'Messages' to display the Warnings and Alarms including information concerning cause and remedy. A detailed description of the events is available in the manual. manual.

≡				Administrator   English
	SINAMICS S210	Demo: Ready		
<b>↑</b>	Diagnostics 🗸	> Messages 🗸		
ŧð	<ul> <li>Search and Filters</li> </ul>			
цо С	_e <sup>O</sup> search	Filter by		
tit				Reset
11 B	Туре	Time received	Alarm	Time removed
85	Alarm	2017-05-09 13:26:42:861	1912: PB/PN. Taktsynchroner Betrieb Lebenszeichenausfall (0)	2017-05-09 13:26:42:862
	Alarm	2017-05-09 13:23:39:354	1912: PB/PN: Taktsynchroner Betrieb Lebenszeichenausfall (0)	2017-05-09 13:23:39:359
¢۲	Alarm	2017-05-09 13:21:42:573	1912: PB/PN: Taktsynchroner Betrieb Lebenszeichenausfall (0)	2017-05-09 13:21:42:574
	Alarm	2017-05-09 13:19:27:422	1912: PB/PN: Taktsynchroner Betrieb Lebenszeichenausfall (0)	2017-05-09 13:19:27:423
	Alarm	2017-05-09 12:14:37:222	1912: PB/PN: Taktsynchroner Betrieb Lebenszeichenausfall (0)	2017-05-09 12:14:37:223
	Alarm	2000-01-06 17:13:48:535	1912: PB/PN: Taktsynchroner Betrieb Lebenszeichenausfall (0)	2000-01-06 17:13:48:535
	🖬 Alam	2017-05-08 14:48:16:178	1912: PB/PN: Taktsynchroner Betrieb Lebenszeichenausfall (0)	2017-05-08 17:11:48:0
	A Warning	2017-05-09 13:29:10:196	1099: UTC Synchronisation Toleranz verletzt (0)	2017-05-09 13:29:10:196
	A Warning	2017-05-09 13:34:52:174	7095: Antrieb: One Button Tuning aktiviert (0)	2017-05-09 13:35:01:881

#### Diagnostics

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# Diagnostic of the converter Besides the diagnose with the Webserver troubleshooting can be done directly on the device. The alarms and faults are shown in the display of the converter according to the message classes defined in PROFIdrive.

- Display and operational elements The converter displays the current operating state via two LEDs
- RDY: Status of the converter
- COM: Status of the communication Faults can be acknowledged with the OK button

When using an SD-Card, push it into the slot (label to the left). When parameters were saved on the card after commissioning, an easy exchange of the converter is possible in case of a defect. Switch the converter off to plug-in or remove the SD card.

#### Message number | Description Hardware/software error Hardware or software malfunction 1 Network fault 2 A line supply fault has occurred (phase failure, voltage level, etc.) Supply voltage fault Power supply fault (24 V) has been identified 3 DC link overvoltage 4 The DC-link voltage is too high Power electronics fault Failure in power electronics (overcurrent, overtemperature, IGBT failure,...) 5 Overtemperature electronic component 6 Temperature of electronics exceeded the highest permissible limit Ground fault / inter-phase short-circuit detected 7 Failure in the power cables or motor windings Motor overload The motor has exceeded its limits 8 Communication error to PLC 9 Interrupted or failed network communications Safety monitoring channel detected an error A safe operation function has detected an error 10 Position actual value/speed value error Encoder signal error detected (track signals, zero marks, absolute values...) 11 Internal (DRIVE-CLiQ) communication error Communications between SINAMICS components is faulty or has been interrupted 12 Fault infeed 13 The infeed is faulty or has failed. Braking controller / Braking Module error Braking Module fault or overloaded 14 Line filter fault 15 The line filter exceeded temperature limits or has non-permissible state External value/signal out of the range Digital/Analog inputs error (or temperature) 16 Application / technology fault Application or technology function has exceeded a limit (position, velocity, torque...) 17 Error in the configuration/commissioning Error in the commissioning procedure, or the configuration of the device 18 General drive fault 19 Group fault Auxiliary unit fault Auxiliary unit has identified an illegal state. 20

### Safety functions





# Correcting faults of the motor

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Fault         Cause of fault (see 'Fault cases and remedial measures' below           Motor does not start         A         B         Image: Construct and the starting         Construct and the startis and on the starting         Construct and the	Correcting faults of the motor																
Motor starts slowly       A       C       F       Image: C       F         Humming sound when starting       C       F       Image: C       F       Image: C       F         Humming sound in operation       A       C       F       Image: C       F       Image: C       F         High temperature rise under no-load       D       Image: C       F       Image: C       F       Image: C       F       Image: C       F       Image: C       Image: C       F       Image: C       F       Image: C       F       Image: C       Image: C       F       Image: C       <	Fault		Cau	se o	f fau	lt (se	e 'Fa	ulto	ases	s and	rem	edia	l me	asur	es' k	elov	/
Humming sound when starting       C       F       I       I         Humming sound in operation       A       C       F       I       I       I         Humming sound in operation       A       C       F       I       <	Motor	does not start	A	В													
Humming sound in operation       A       C       F       I       I         High temperature rise under no-load       D       I <td< td=""><td></td><td></td><td>A</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></td<>			A														
High temperature rise under no-load       D       I																	
Operation       I			A		C		F										
High temperature rise under load A C I I I I I I I I I I I I I I I I I I	High te	emperature rise under no-load				D											
High temperature rise of individual       F       Image: Construction of the second of the se	Uperat High to	ION moerature rise under load		-		<u> </u>		-									$\left  - \right $
Winding Sections       J       K       J       K       J         Grinding sound, running noise       J       J       K       L <t< td=""><td>High te</td><td>emperature rise of individual</td><td></td><td> </td><td></td><td></td><td>_</td><td>1</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td><math>\left  - \right </math></td></t<>	High te	emperature rise of individual					_	1									$\left  - \right $
Grinding sound, running noise       L       L       M       N       O       P       R         Radial vibrations       I       I       I       I       M       N       O       P       R         Axial vibrations       I       <	Iwindin	a sections					F										
Grinding sound, running noise       L       L       M       N       O       P       R         Radial vibrations       I       I       I       I       M       N       O       P       R         Axial vibrations       I       <	Uneve	n running							J	Κ						1	
Axial vibrations       Image: Note of the second seco					1						L			1		1	
No.         Fault cause         Remedial measures           A         Overload         Reduce load           B         Interruption of a phase in the supply cable / motor winding         Check the converter and supply cables, measure the winding resistances and insulation resistances, repair after consultation with manufacturer           C         Interrupted phase in the feeder cable after switching on         Check the frequency converter, supply cables and the winding resistances           D         Converter output voltage too high, frequency too low         Check the settings on the frequency converter, perform automatic motor identification           F         Winding short-circuit or phase short- circuit in stator winding         Measure the winding resistances and insulation resistances, repair after consultation with the manufacturer, if required, replace the motor           I         Heat dissipation impeded by deposits         Clean the surface of the drives and ensure that the cooling air can flow in and out unimpeded           J         Insufficient shielding for motor and/ or encoder cable         Check the shielding and grounding           K         Excessive drive controller gain         Adjust the controller           Replace the motor         Replace the motor           Bearing damage         Replace the motor           Motions inside the motor         Replace the motor           Bearing damage         Replace the motor           Motor not balan												М	Ν	0	Р		R
A       Overload       Reduce load         B       Interruption of a phase in the supply cable / motor winding       Check the converter and supply cables, measure the winding resistances and insulation resistances, repair after consultation with manufacturer         C       Interrupted phase in the feeder cable after switching on       Check the frequency converter, supply cables and the winding resistances         D       Converter output voltage too high, frequency too low       Check the settings on the frequency converter, perform automatic motor identification         F       Winding short-circuit or phase short- circuit in stator winding       Measure the winding resistances and insulation resistances, repair after consultation with the manufacturer, if required, replace the motor         I       Heat dissipation impeded by deposits       Clean the surface of the drives and ensure that the cooling air can flow in and out unimpeded         J       Insufficient shielding for motor and/ or encoder cable       Remove the reason for the blocking and ensure that the cooling air can flow in and out unimpeded         K       Excessive drive controller gain       Adjust the controller         Rotating parts are grinding       Determine cause and adjust parts         Foreign bodies inside the motor       Replace the motor         Bearing damage       Replace the motor         Matting parts are grinding       Determine cause and adjust parts         Foreign bodies inside the motor       Replac	Axial v	ribrations												0		Q	R
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B       Interruption of a phase in the supply cable / motor winding       resistances and insulation resistances, repair after consultation with manufacturer         C       Interrupted phase in the feeder cable after switching on       Check the frequency converter, supply cables and the winding resistances         D       Converter output voltage too high, frequency too low       Check the settings on the frequency converter, perform automatic motor identification         F       Winding short-circuit or phase short-circuit in stator winding       Measure the winding resistances and insulation resistances, repair after consultation with the manufacturer, if required, replace the motor         I       Heat dissipation impeded by deposits       Clean the surface of the drives and ensure that the cooling air can flow in and out unimpeded         J       Insufficient shielding for motor and/or encoder cable       Remove the reason for the blocking and ensure that the cooling air can flow in and out unimpeded         J       Insufficient shielding for motor and/or encoder cable       Check the shielding and grounding         K       Excessive drive controller gain       Adjust the controller         L       Foreign bodies inside the motor       Replace the motor         Bearing damage       Replace the motor       Replace the motor         Rotating parts are grinding       Determine cause and adjust parts       Poreign bodies inside the motor         Rotor out of true, shaft bent       Consult the ma	А	Overload		F	Redu	ce loa	ad										
C       cable after switching on       resistances       resistances         D       Converter output voltage too high, frequency too low       Check the settings on the frequency converter, perform automatic motor identification         F       Winding short-circuit or phase short-circuit in stator winding       Measure the winding resistances and insulation resistances, repair after consultation with the manufacturer, if required, replace the motor         I       Heat dissipation impeded by deposits       Clean the surface of the drives and ensure that the cooling air can flow in and out unimpeded         J       Insufficient shielding for motor and/ or encoder cable       Remove the reason for the blocking and ensure that the cooling air can flow in and out unimpeded         K       Excessive drive controller gain       Adjust the controller         Rotating parts are grinding       Determine cause and adjust parts         Foreign bodies inside the motor       Replace the motor         M       Rotor not balanced       Replace the motor         M       Rotor out of true, shaft bent       Consult the manufacturer         O       Poor alignment       Align motor set, check coupling         P       Coupled machine not balanced       Re-balance coupled machine	В	Interruption of a phase in the supply cable / motor winding				resistances and insulation resistances, repair after											
B       frequency too low       automatic motor identification         F       Winding short-circuit or phase short-circuit in stator winding       Measure the winding resistances and insulation resistances, repair after consultation with the manufacturer, if required, replace the motor         I       Heat dissipation impeded by deposits       Clean the surface of the drives and ensure that the cooling air can flow in and out unimpeded         I       Cooling air inlet/outlet is blocked by foreign bodies       Remove the reason for the blocking and ensure that the cooling air can flow in and out unimpeded         J       Insufficient shielding for motor and/or encoder cable       Check the shielding and grounding         K       Excessive drive controller gain       Adjust the controller         L       Foreign bodies inside the motor       Replace the motor         Bearing damage       Replace the motor       Replace the motor         M       Rotor not balanced       Replace the motor         N       Rotor out of true, shaft bent       Consult the manufacturer         O       Poor alignment       Align motor set, check coupling         P       Coupled machine not balanced       Re-balance coupled machine	С		r														
F       Winding short-circuit or phase short-circuit in stator winding       repair after consultation with the manufacturer, if required, replace the motor         I       Heat dissipation impeded by deposits       Clean the surface of the drives and ensure that the cooling air can flow in and out unimpeded         I       Cooling air inlet/outlet is blocked by foreign bodies       Remove the reason for the blocking and ensure that the cooling air can flow in and out unimpeded         J       Insufficient shielding for motor and/ or encoder cable       Check the shielding and grounding         K       Excessive drive controller gain       Adjust the controller         L       Foreign bodies inside the motor       Replace the motor         Bearing damage       Replace the motor         M       Rotor out of true, shaft bent       Consult the manufacturer         O       Poor alignment       Align motor set, check coupling         P       Coupled machine not balanced       Re-balance coupled machine         Q       Shocks from coupled machine       Check coupled machine	D		igh,	a	Check the settings on the frequency converter, perform automatic motor identification												
I         deposits         can flow in and out unimpeded           I         Cooling air inlet/outlet is blocked by foreign bodies         Remove the reason for the blocking and ensure that the cooling air can flow in and out unimpeded           J         Insufficient shielding for motor and/ or encoder cable         Check the shielding and grounding           K         Excessive drive controller gain         Adjust the controller           Rotating parts are grinding         Determine cause and adjust parts           L         Foreign bodies inside the motor         Replace the motor           Bearing damage         Replace the motor           M         Rotor not balanced         Replace the motor           N         Rotor out of true, shaft bent         Consult the manufacturer           O         Poor alignment         Align motor set, check coupling           P         Coupled machine not balanced         Re-balance coupled machine           Q         Shocks from coupled machine         Check coupled machine	F	Winding short-circuit or phase circuit in stator winding	shor	τ-   n	repair after consultation with the manufacturer, if required,												
Cooling air inlet/outlet is blocked by foreign bodies         Remove the reason for the blocking and ensure that the cooling air can flow in and out unimpeded           J         Insufficient shielding for motor and/ or encoder cable         Check the shielding and grounding           K         Excessive drive controller gain         Adjust the controller           Rotating parts are grinding         Determine cause and adjust parts           L         Foreign bodies inside the motor         Replace the motor           Bearing damage         Replace the motor           N         Rotor not balanced         Replace the motor           N         Rotor out of true, shaft bent         Consult the manufacturer           O         Poor alignment         Align motor set, check coupling           P         Coupled machine not balanced         Re-balance coupled machine           Q         Shocks from coupled machine         Check coupled machine																	
J         or encoder cable         Check the shielding and grounding           K         Excessive drive controller gain         Adjust the controller           Rotating parts are grinding         Determine cause and adjust parts           Foreign bodies inside the motor         Replace the motor           Bearing damage         Replace the motor           M         Rotor not balanced         Replace the motor           N         Rotor out of true, shaft bent         Consult the manufacturer           O         Poor alignment         Align motor set, check coupling           P         Coupled machine not balanced         Re-balance coupled machine           Q         Shocks from coupled machine         Check coupled machine	1		ed by	/ F	Remove the reason for the blocking and ensure that the cooling air can flow in and out unimpeded												
Rotating parts are grinding         Determine cause and adjust parts           L         Foreign bodies inside the motor         Replace the motor           Bearing damage         Replace the motor           M         Rotor not balanced         Replace the motor           N         Rotor out of true, shaft bent         Consult the manufacturer           O         Poor alignment         Align motor set, check coupling           P         Coupled machine not balanced         Re-balance coupled machine           Q         Shocks from coupled machine         Check coupled machine	J		and/	0	Check the shielding and grounding												
L         Foreign bodies inside the motor         Replace the motor           Bearing damage         Replace the motor           M         Rotor not balanced         Replace the motor           N         Rotor out of true, shaft bent         Consult the manufacturer           O         Poor alignment         Align motor set, check coupling           P         Coupled machine not balanced         Re-balance coupled machine           Q         Shocks from coupled machine         Check coupled machine	К	Excessive drive controller gair	1	A	Adjust the controller												
L         Foreign bodies inside the motor         Replace the motor           Bearing damage         Replace the motor           M         Rotor not balanced         Replace the motor           N         Rotor out of true, shaft bent         Consult the manufacturer           O         Poor alignment         Align motor set, check coupling           P         Coupled machine not balanced         Re-balance coupled machine           Q         Shocks from coupled machine         Check coupled machine		Rotating parts are grinding															
M         Rotor not balanced         Replace the motor           N         Rotor out of true, shaft bent         Consult the manufacturer           O         Poor alignment         Align motor set, check coupling           P         Coupled machine not balanced         Re-balance coupled machine           Q         Shocks from coupled machine         Check coupled machine	L		or	F	Repla	ce th	e mo	tor									
N         Rotor out of true, shaft bent         Consult the manufacturer           O         Poor alignment         Align motor set, check coupling           P         Coupled machine not balanced         Re-balance coupled machine           Q         Shocks from coupled machine         Check coupled machine		Bearing damage	F												_		
O         Poor alignment         Align motor set, check coupling           P         Coupled machine not balanced         Re-balance coupled machine           Q         Shocks from coupled machine         Check coupled machine	М	Rotor not balanced	F														
P         Coupled machine not balanced         Re-balance coupled machine           Q         Shocks from coupled machine         Check coupled machine	Ν	Rotor out of true, shaft bent		0	Consi	ult the	e mai	nufa	cture	-							
Q Shocks from coupled machine Check coupled machine				A													
Q Shocks from coupled machine Check coupled machine	Р	Coupled machine not balance	b								-						
R Fault originating from the gearbox Adjust/repair gearbox	Q			0	Checl	< cou	pled	mac	hine								
	R	Fault originating from the gear	box	A	Adjus	t/repa	air ge	arbo	X								

SIMATIC S210 Operating Instructio www.siemens.com



#### Underwriters Laboratories

For United States / Canadian installations (UL/cUL): The products are cULus listed under File E355661 Vol. 3 Sec. 8.

Solid State Motor Overload Protection: 300% of motor FLA.

Suitable for use on a circuit capable of delivering not more than 65 kA rms (symmetrical), 240 V maximum. Branch circuit protection for individual drives shall be provided by Class J fuses stated in Technical Data. Branch circuit protection for group installation shall be provided by 30 Amps Class J fuses.

For further protective devices and SCCRs for individual drives and group installation refer to:

https://support.industry.siemens.com/cs/document/109748999

This equipment is to be installed in an enclosure that provides a pollution degree 2 (controlled) environment. Equipment does not provide internal motor overtemperature protection. Overtemperature protection is provided by evaluation of thermal sensor.

Use 75°C rated copper wires for all power conductors.

Additional requirements for CSA compliance:

Overvoltage Category OVC III must be ensured for all primary circuit connections of the equipment. This may require Surge Protective Devices (SPD) to be installed on the line side of the equipment. The SPDs shall be rated 240V (phase to phase and phase to ground) and shall provide protection for a rated impulse withstand voltage peak of 4kV.

> Siemens AG Digital Factory Motion Contro Postfach 3180 91050 ERLANGEN Germany

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